

Infinite Strategies in Two-Player Games

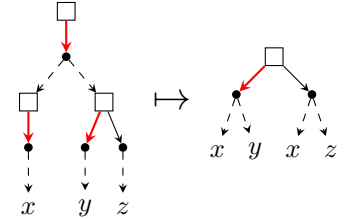
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The coalgebraic study of infinite linear-time semantics was initiated by Jacobs in [4], where it was shown that linear-time semantics in labelled transition systems cannot be captured by finality in a Kleisli category, but instead by the *greatest* coalgebra morphism. This contribution describes some recent work [8], about infinite linear-time semantics in the richer structure of a *two-player game*: a transition system with two flavours of non-determinism. The semantics at a state in the game is described by the set of strategies starting from that state; we find that the infinite trace map, assigning states to semantics, can be computed as a greatest, and least, fixed point.

Our motivation for studying two-player games stems from their use in reactive synthesis. The problem of controller synthesis can be phrased as constructing a *strategy*, a function which prescribes a move in the game based on the history of the play, subject to some *correctness* and *optimality* requirements. Hence, understanding the linear-time semantics (i.e. strategies) is vital in this setting. In the future, we see that coalgebra should play a role in extending these techniques from qualitative settings to quantitative settings (e.g. when the environment is probabilistic).

To obtain a linear-time semantics, the key aspect of the coalgebraic approach is to identify a *monad* to model the branching type. The classical case of labelled transition systems uses the *powerset monad* $P : \mathbf{Set} \rightarrow \mathbf{Set}$, where the *monad multiplication* $\cup : PP \rightarrow P$ lets us flatten multiple steps into one. What enables us to model two-player games is identifying a suitable monad $\mathcal{G} : \mathbf{Set} \rightarrow \mathbf{Set}$ to model the branching structure of games, provided by work on alternating automata in [2] (and implicitly in [5]). The set $\mathcal{G}(X)$ consists of sets of non-empty subsets which are closed under arbitrary non-empty union, and the monad multiplication $\mu^{\mathcal{G}} : \mathcal{G}\mathcal{G}(X) \rightarrow \mathcal{G}(X)$ maps $\alpha \in \mathcal{G}\mathcal{G}(X) \mapsto \{\bigcup_{U \in \beta} U \mid \exists \beta \in \alpha, \forall U \in \beta : U \in \mathcal{U}\}$. We see $\mu^{\mathcal{G}}$ as flattening two sequential moves in the game into a single move, as depicted on the right. We have not explicitly drawn choices which are unions of others, we see these choices as letting the \square player leave choices undetermined.



One-player Models We briefly describe the situation for one-player models (essentially from [4]), before describing our results for games. We can model a labelled transition system as a function $\alpha : X \rightarrow PF(X)$, where for simplicity we take the functor $F : \mathbf{Set} \rightarrow \mathbf{Set}$ to be $A \times (-)$. The terminal coalgebra for F is A^ω equipped with $\zeta : A^\omega \rightarrow A \times A^\omega$, where A^ω denotes the set of infinite words over A . As with every monad, there is a functor $\overline{(-)} : \mathbf{Set} \rightarrow \mathbf{Kl}(P)$ which composes a function with the unit η^P of P . We will denote $\mathbf{Kl}(P)$ maps with $\dashv\rightarrow$, it is well-known that these are *relations* (i.e. that $\mathbf{Kl}(P) \cong \mathbf{Rel}$), and that F lifts to a functor \overline{F} on \mathbf{Rel} . Also recall that each homset in \mathbf{Rel} naturally carries a complete lattice structure.

Viewing (X, α) as an \overline{F} -coalgebra, we can study the complete lattice of relations $X \dashv\rightarrow A^\omega$, equipped with a monotone function Φ which maps $(X \dashv\rightarrow A^\omega) \mapsto (X \xrightarrow{\alpha} F(X) \xrightarrow{\overline{F}(f)} F(A^\omega) \xrightarrow{\zeta^{-1}} A^\omega)$. It is known that the *greatest fixed point* of Φ gives us a good notion of *infinite trace map* $X \dashv\rightarrow A^\omega$, which maps a state to all of the infinite traces which can arise from said state.

Another view is presented in [6], which phrases infinite traces as a categorical limit of the n -step unfoldings. A biproduct of the investigation in [8] is showing that these approaches are equivalent.

Games Many of the same facts carry over to the two-player setting. We denote maps in $\mathbf{Kl}(\mathcal{G})$ with $\dashv\rightarrow$, and again it is known that $F = A \times (-)$ lifts to a functor $\overline{F} : \mathbf{Kl}(\mathcal{G}) \rightarrow \mathbf{Kl}(\mathcal{G})$. The space of maps $X \dashv\rightarrow Y$ form a complete lattice. We model a game with an \overline{F} -coalgebra $\gamma : X \dashv\rightarrow F(X)$, and have a monotone function Φ on $\mathbf{Kl}(\mathcal{G})(X, A^\omega)$ given by $(X \dashv\rightarrow A^\omega) \mapsto (X \xrightarrow{\gamma} F(X) \xrightarrow{\overline{F}(f)} F(A^\omega) \xrightarrow{\zeta^{-1}} A^\omega)$. Notice that our games are fundamentally from \square 's perspective, when we speak of “a strategy” we mean a strategy for \square .

While in the one-player case, it is clear what the infinite trace map $X \rightarrow A^\omega$ should be, the question is more subtle for the infinite trace map $X \rightarrow A^\omega$ in games. This was tackled conclusively for finite traces in [7], by instantiating the coalgebraic approach to finite traces in [3] to games. It was shown in loc. cit. that the *finite* trace map assigns each state the set of subsets of *finite* traces which can be forced by a *finitely completing* strategy in the game. This insight leads us to define the *infinite trace semantics* at a state in the game, as the set consisting of subsets of A^ω which can be forced by some strategy from said state. One way to view this definition is that the correct generalisation of a *path* through a single-player model, is a *strategy* in a game, because both arise from a sequence of choices. The infinite trace map will assign each state to its infinite trace semantics, in [8], we find that this map is *not* the greatest, or least, fixed point of Φ .

Despite this negative result, we can still recover the infinite trace map as a greatest fixed point, just on a smaller lattice. For the restriction, we require the notion of *limit-closure* used in the semantics of temporal logic [1]. A subset $U \subseteq A^\omega$ is *limit-closed* when for any $p \in A^\omega$, if we can find every prefix of p in U (followed by some suffix), then we find that $p \in U$. This is a natural condition when we consider that the subset of plays which conform to a strategy is always limit-closed. We also technically work with *executions* rather than traces, by using $F = X \times A \times (-)$ and assuming that the game records state information.

Theorem 1 ([8]). *We can restrict $\mathbf{Kl}(\mathcal{G})(X, (XA)^\omega)$ and Φ to the set of maps $f : X \rightarrow \mathcal{G}((XA)^\omega)$ where each $U \in f(x)$ is limit-closed. The greatest fixed point in this lattice recovers the infinite trace map.*

We can even see the infinite trace map as being approximated by the least fixed point.

Theorem 2 ([8]). *Let (X, γ) be a game with no deadlocks (i.e. $\gamma(x) \neq \emptyset$). We can restrict $\mathbf{Kl}(\mathcal{G})(X, (XA)^\omega)$ and Φ to the collection of maps $f : X \rightarrow \mathcal{G}((XA)^\omega)$ where there is some $U \in f(x)$ which corresponds to \square leaving all choices undetermined on (X, γ) . Take the least fixed point $f : X \rightarrow \mathcal{G}((XA)^\omega)$ in this lattice, if we close each $f(x)$ under intersections of descending chains, we obtain the infinite trace map.*

Theorem 2 can be viewed as *strategy refinement*: where one starts with the maximally permissive strategy at each state, and then refines strategies in an inductive fashion (with Φ). This explains the assumption that there are no deadlocks, as this is required for there to exist a maximally permissive strategy from every state. A consequence is that we can approximate any infinite memory strategy with a sequence of finite memory strategies.

References

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